

NAG Fortran Library Routine Document

F07CVF (ZGTRFS)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

F07CVF (ZGTRFS) computes error bounds and refines the solution to a complex system of linear equations $AX = B$ or $A^T X = B$ or $A^H X = B$, where A is an n by n tridiagonal matrix and X and B are n by r matrices, using the LU factorization returned by F07CRF (ZGTTRF) and an initial solution returned by F07CSF (ZGTTRS). Iterative refinement is used to reduce the backward error as much as possible.

2 Specification

```

SUBROUTINE F07CVF (TRANS, N, NRHS, DL, D, DU, DLF, DF, DUF, DU2, IPIV,
1          B, LDB, X, LDX, FERR, BERR, WORK, RWORK, INFO)
INTEGER          N, NRHS, IPIV(*), LDB, LDX, INFO
double precision FERR(*), BERR(*), RWORK(*)
complex*16      DL(*), D(*), DU(*), DLF(*), DF(*), DUF(*), DU2(*),
1          B(LDB,*), X(LDX,*), WORK(*)
CHARACTER*1     TRANS

```

The routine may be called by its LAPACK name *zgtrfs*.

3 Description

F07CVF (ZGTRFS) should normally be preceded by calls to F07CRF (ZGTTRF) and F07CSF (ZGTTRS). F07CRF (ZGTTRF) uses Gaussian elimination with partial pivoting and row interchanges to factorize the matrix A as

$$A = PLU,$$

where P is a permutation matrix, L is unit lower triangular with at most one non-zero subdiagonal element in each column, and U is an upper triangular band matrix, with two superdiagonals. F07CSF (ZGTTRS) then utilizes the factorization to compute a solution, \hat{X} , to the required equations. Letting \hat{x} denote a column of \hat{X} , F07CVF (ZGTRFS) computes a *component-wise backward error*, β , the smallest relative perturbation in each element of A and b such that \hat{x} is the exact solution of a perturbed system

$$(A + E)\hat{x} = b + f, \quad \text{with } |e_{ij}| \leq \beta|a_{ij}|, \quad \text{and } |f_j| \leq \beta|b_j|.$$

The routine also estimates a bound for the *component-wise forward error* in the computed solution defined by $\max |x_i - \hat{x}_i| / \max |\hat{x}_i|$, where x is the corresponding column of the exact solution, X .

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia URL: <http://www.netlib.org/lapack/lug>

5 Parameters

1: TRANS – CHARACTER*1 *Input*

On entry: specifies the equations to be solved as follows:

TRANS = 'N'

Solve $AX = B$ for X .

TRANS = 'T'

Solve $A^T X = B$ for X .

TRANS = 'C'

Solve $A^H X = B$ for X .

Constraint: TRANS = 'N', 'T' or 'C'.

- 2: N – INTEGER *Input*
On entry: n , the order of the matrix A .
Constraint: $N \geq 0$.
- 3: NRHS – INTEGER *Input*
On entry: r , the number of right-hand sides, i.e., the number of columns of the matrix B .
Constraint: NRHS ≥ 0 .
- 4: DL(*) – **complex*16** array *Input*
Note: the dimension of the array DL must be at least $\max(1, N - 1)$.
On entry: must contain the $(n - 1)$ subdiagonal elements of the matrix A .
- 5: D(*) – **complex*16** array *Input*
Note: the dimension of the array D must be at least $\max(1, N)$.
On entry: must contain the n diagonal elements of the matrix A .
- 6: DU(*) – **complex*16** array *Input*
Note: the dimension of the array DU must be at least $\max(1, N - 1)$.
On entry: must contain the $(n - 1)$ superdiagonal elements of the matrix A .
- 7: DLF(*) – **complex*16** array *Input*
Note: the dimension of the array DLF must be at least $\max(1, N - 1)$.
On entry: must contain the $(n - 1)$ multipliers that define the matrix L of the LU factorization of A .
- 8: DF(*) – **complex*16** array *Input*
Note: the dimension of the array DF must be at least $\max(1, N)$.
On entry: must contain the n diagonal elements of the upper triangular matrix U from the LU factorization of A .
- 9: DUF(*) – **complex*16** array *Input*
Note: the dimension of the array DUF must be at least $\max(1, N - 1)$.
On entry: must contain the $(n - 1)$ elements of the first superdiagonal of U .
- 10: DU2(*) – **complex*16** array *Input*
Note: the dimension of the array DU2 must be at least $\max(1, N - 2)$.
On entry: must contain the $(n - 2)$ elements of the second superdiagonal of U .

- 11: IPIV(*) – INTEGER array *Input*
Note: the dimension of the array IPIV must be at least $\max(1, N)$.
On entry: must contain the n pivot indices that define the permutation matrix P . At the i th step, row i of the matrix was interchanged with row IPIV(i), and IPIV(i) must always be either i or $(i + 1)$, IPIV(i) = i indicating that a row interchange was not performed.
- 12: B(LDB,*) – **complex*16** array *Input*
Note: the second dimension of the array B must be at least $\max(1, NRHS)$.
On entry: the n by r matrix of right-hand sides B .
- 13: LDB – INTEGER *Input*
On entry: the first dimension of the array B as declared in the (sub)program from which F07CVF (ZGTRFS) is called.
Constraint: $LDB \geq \max(1, N)$.
- 14: X(LDX,*) – **complex*16** array *Input/Output*
Note: the second dimension of the array X must be at least $\max(1, NRHS)$.
On entry: the n by r initial solution matrix X .
On exit: the n by r refined solution matrix X .
- 15: LDX – INTEGER *Input*
On entry: the first dimension of the array X as declared in the (sub)program from which F07CVF (ZGTRFS) is called.
Constraint: $LDX \geq \max(1, N)$.
- 16: FERR(*) – **double precision** array *Output*
Note: the dimension of the array FERR must be at least $\max(1, NRHS)$.
On exit: estimate of the forward error bound for each computed solution vector, such that $\|\hat{x}_j - x_j\|_\infty / \|x_j\|_\infty \leq FERR(j)$, where \hat{x}_j is the j th column of the computed solution returned in the array X and x_j is the corresponding column of the exact solution X . The estimate is almost always a slight overestimate of the true error.
- 17: BERR(*) – **double precision** array *Output*
Note: the dimension of the array BERR must be at least $\max(1, NRHS)$.
On exit: estimate of the component-wise relative backward error of each computed solution vector \hat{x}_j (i.e., the smallest relative change in any element of A or B that makes \hat{x}_j an exact solution).
- 18: WORK(*) – **complex*16** array *Workspace*
Note: the dimension of the array WORK must be at least $\max(1, 2 \times N)$.
- 19: RWORK(*) – **double precision** array *Workspace*
Note: the dimension of the array RWORK must be at least $\max(1, N)$.
- 20: INFO – INTEGER *Output*
On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

INFO < 0

If INFO = $-i$, the i th argument had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The computed solution for a single right-hand side, \hat{x} , satisfies an equation of the form

$$(A + E)\hat{x} = b,$$

where

$$\|E\|_{\infty} = O(\epsilon)\|A\|_{\infty}$$

and ϵ is the *machine precision*. An approximate error bound for the computed solution is given by

$$\frac{\|\hat{x} - x\|_{\infty}}{\|x\|_{\infty}} \leq \kappa(A) \frac{\|E\|_{\infty}}{\|A\|_{\infty}},$$

where $\kappa(A) = \|A^{-1}\|_{\infty}\|A\|_{\infty}$, the condition number of A with respect to the solution of the linear equations. See Section 4.4 of Anderson *et al.* (1999) for further details.

Routine F07CUF (ZGTCON) can be used to estimate the condition number of A .

8 Further Comments

The total number of floating-point operations required to solve the equations $AX = B$ or $A^T X = B$ or $A^H X = B$ is proportional to nr . At most five steps of iterative refinement are performed, but usually only one or two steps are required.

The real analogue of this routine is F07CHF (DGTRFS).

9 Example

This example solves the equations

$$AX = B,$$

where A is the tridiagonal matrix

$$A = \begin{pmatrix} -1.3 + 1.3i & 2.0 - 1.0i & 0 & 0 & 0 \\ 1.0 - 2.0i & -1.3 + 1.3i & 2.0 + 1.0i & 0 & 0 \\ 0 & 1.0 + 1.0i & -1.3 + 3.3i & -1.0 + 1.0i & 0 \\ 0 & 0 & 2.0 - 3.0i & -0.3 + 4.3i & 1.0 - 1.0i \\ 0 & 0 & 0 & 1.0 + 1.0i & -3.3 + 1.3i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 2.4 - 5.0i & 2.7 + 6.9i \\ 3.4 + 18.2i & -6.9 - 5.3i \\ -14.7 + 9.7i & -6.0 - 0.6i \\ 31.9 - 7.7i & -3.9 + 9.3i \\ -1.0 + 1.6i & -3.0 + 12.2i \end{pmatrix}.$$

Estimates for the backward errors and forward errors are also output.

9.1 Program Text

```

*      F07CVF Example Program Text
*      Mark 21 Release. NAG Copyright 2004.
*      .. Parameters ..
INTEGER          NIN, NOUT
PARAMETER       (NIN=5,NOUT=6)
INTEGER          NMAX, NRHSMX
PARAMETER       (NMAX=50,NRHSMX=4)
INTEGER          LDB, LDX
PARAMETER       (LDB=NMAX,LDX=NMAX)
*      .. Local Scalars ..
INTEGER          I, IFAIL, INFO, J, N, NRHS
*      .. Local Arrays ..
COMPLEX *16     B(LDB,NRHSMX), D(NMAX), DF(NMAX), DL(NMAX-1),
+              DLF(NMAX-1), DU(NMAX-1), DU2(NMAX-2),
+              DUF(NMAX-1), WORK(2*NMAX), X(LDX,NRHSMX)
DOUBLE PRECISION BERR(NRHSMX), FERR(NRHSMX), RWORK(NMAX)
INTEGER          IPIV(NMAX)
CHARACTER       CLABS(1), RLABS(1)
*      .. External Subroutines ..
EXTERNAL        F06TFF, X04DBF, ZCOPY, ZGTRFS, ZGTTRF, ZGTTTRS
*      .. Executable Statements ..
WRITE (NOUT,*) 'F07CVF Example Program Results'
WRITE (NOUT,*)
*      Skip heading in data file
READ (NIN,*)
READ (NIN,*) N, NRHS
IF (N.LE.NMAX .AND. NRHS.LE.NRHSMX) THEN
*
*      Read the tridiagonal matrix A from data file
*
*      READ (NIN,*) (DU(I),I=1,N-1)
*      READ (NIN,*) (D(I),I=1,N)
*      READ (NIN,*) (DL(I),I=1,N-1)
*
*      Read the right hand matrix B
*
*      READ (NIN,*) ((B(I,J),J=1,NRHS),I=1,N)
*
*      Copy A into DUF, DF and DLF, and copy B into X
*
*      CALL ZCOPY(N-1,DU,1,DUF,1)
*      CALL ZCOPY(N,D,1,DF,1)
*      CALL ZCOPY(N-1,DL,1,DLF,1)
*      CALL F06TFF('General',N,NRHS,B,LDB,X,LDX)
*
*      Factorize the copy of the tridiagonal matrix A
*
*      CALL ZGTTRF(N,DLF,DF,DUF,DU2,IPIV,INFO)
*
*      IF (INFO.EQ.0) THEN
*
*      Solve the equations AX = B
*
*      CALL ZGTTTRS('No transpose',N,NRHS,DLF,DF,DUF,DU2,IPIV,X,LDX,
+              INFO)
*
*      Improve the solution and compute error estimates
*
*      CALL ZGTRFS('No transpose',N,NRHS,DL,D,DU,DLF,DF,DUF,DU2,
+              IPIV,B,LDB,X,LDX,FERR,BERR,WORK,RWORK,INFO)
*
*      Print the solution and the forward and backward error
*      estimates
*
*      IFAIL = 0
*      CALL X04DBF('General',' ',N,NRHS,X,LDX,'Bracketed','F7.4',
+              'Solution(s)','Integer',RLABS,'Integer',CLABS,
+              80,0,IFAIL)
*

```

```

      WRITE (NOUT,*)
      WRITE (NOUT,*) 'Backward errors (machine-dependent)'
      WRITE (NOUT,99999) (BERR(J),J=1,NRHS)
      WRITE (NOUT,*)
      WRITE (NOUT,*)
+     'Estimated forward error bounds (machine-dependent)'
      WRITE (NOUT,99999) (FERR(J),J=1,NRHS)
    ELSE
      WRITE (NOUT,99998) 'The (', INFO, ', ', INFO, ')',
+     ' element of the factor U is zero'
    END IF
  ELSE
    WRITE (NOUT,*) 'NMAX and/or NRHSMX too small'
  END IF
STOP
*
99999 FORMAT ((3X,1P,7E11.1))
99998 FORMAT (1X,A,I3,A,I3,A,A)
END

```

9.2 Program Data

F07CVF Example Program Data

```

  5      2                                     :Values of N and NRHS
(  2.0, -1.0) (  2.0,  1.0) ( -1.0,  1.0) (  1.0, -1.0) :End of DU
( -1.3,  1.3) ( -1.3,  1.3) ( -1.3,  3.3) ( -0.3,  4.3)
( -3.3,  1.3)                                     :End of D
(  1.0, -2.0) (  1.0,  1.0) (  2.0, -3.0) (  1.0,  1.0) :End of DL
(  2.4, -5.0) (  2.7,  6.9)
(  3.4, 18.2) ( -6.9, -5.3)
(-14.7,  9.7) ( -6.0, -0.6)
( 31.9, -7.7) ( -3.9,  9.3)
( -1.0,  1.6) ( -3.0, 12.2)                                     :End of B

```

9.3 Program Results

F07CVF Example Program Results

Solution(s)

```

           1           2
1 ( 1.0000, 1.0000) ( 2.0000,-1.0000)
2 ( 3.0000,-1.0000) ( 1.0000, 2.0000)
3 ( 4.0000, 5.0000) (-1.0000, 1.0000)
4 (-1.0000,-2.0000) ( 2.0000, 1.0000)
5 ( 1.0000,-1.0000) ( 2.0000,-2.0000)

```

Backward errors (machine-dependent)

```

  2.2E-17    1.0E-16

```

Estimated forward error bounds (machine-dependent)

```

  5.3E-14    7.7E-14

```